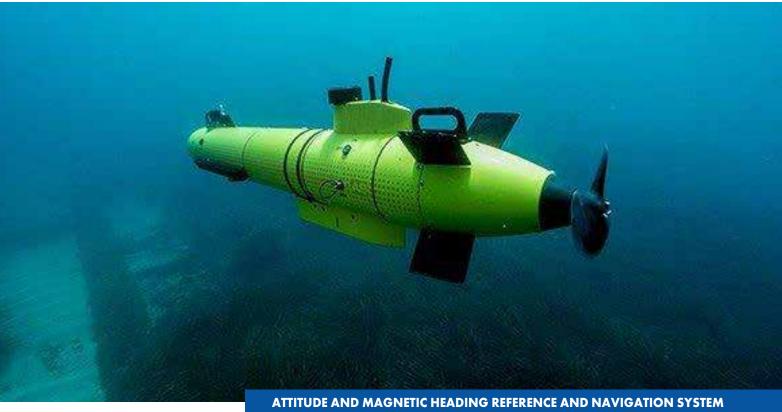
## **MRS-011**





## Main Features

- $\cdot$  Real-time reliable data in marine dynamic environments
- · Drift free attitude data
- · Proprietary Kalman filter algorithm based on cutting-edge data fusion
- · Compact / lightweight
- · Engine magnetic field compensation

Ideal for:

Marine stabilization systems

Unmanned surface platforms

Compact underwater ROV

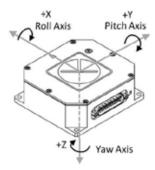


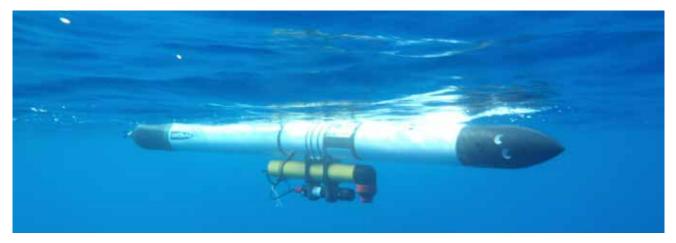
MRS-011 is an attitude measurement system based on high quality MEMS sensors, integrating GEM proprietary algorithms based on Kalman Filters for platform attitude over time, the calculation of heading and the routing of navigation data coming from the GPS/DVL/USBL.

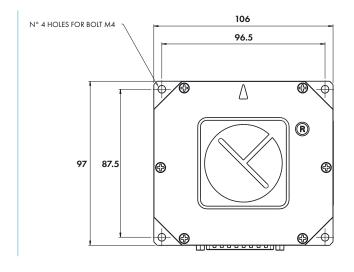
## Standalone attitude measurement system based on high-quality MEMS sensors

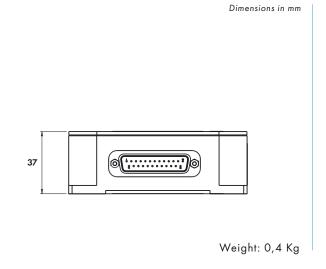
Attitude	
Roll and Pitch Accuracy [RMS]	< 0.25 °
Magnetic heading Accuracy [RMS]	< 1° after calibration
Roll Range	± 180°
Pitch Range	± 90°
Resolution	0.01°
Linear Acceleration	
Range X/Y/Z	± 10 m/ sec <sup>2</sup>
Resolution	$0.00036  \text{m/sec}^2$
Bandwidth	40 Hz
Angular Rate	
Range Roll/Pitch/Yaw	± 300°/sec
Resolution	0.008 °/sec
Bandwidth	40 Hz

Start-up Time	
Start-up Time Valid data	5 sec
fully stabilized data	30 sec
Other	
Jpdate Rate	100 Hz
Operating Temperatures	-0/+50° C
Storing Temperatures	-40/+70° C
Input Power Supply	12 to 32 VDC











This brochure should not be considered a contractual offer. The specifications given herein may be changed by the manufacturer, GEM elettronica, without notice.



